

1. (Currently Amended) A remotely controlled toy vehicle system, comprising:
a remote control signal transmitter for transmitting control signals;
a master model vehicle containing a remote control signal receiver, wherein said master model vehicle is controlled by said control signals as it travels ~~in~~ along a first pathway;
at least one slave model vehicle that is physically connected to said master model vehicle by at least one linkage element that extends from said master model vehicle at a predetermined angle, wherein said at least one slave model vehicle is oriented in a formation with said master model vehicle and is propelled in said formation by said master model vehicle along at least one second pathway that is separate and distinct from said first pathway of said master model vehicle; and
a motor contained within said master model vehicle for selectively adjusting said predetermined angle, wherein motor is controlled by said remote controlled transmitter.

2.(Cancelled)

3. (Currently Amended) The system according to Claim 2 1, wherein said formation is selectively adjustable by said remote control transmitter.

4. (Cancelled)

5.(Cancelled)

6.(Previously Presented) The system according to Claim 1, having multiple slave model vehicles, wherein some of said slave model vehicles are interconnected to each other by secondary linkage elements that are not coupled to said master model vehicle.

7.(Original) The system according to Claim 1, wherein said master model vehicle and said at least one slave model vehicle are selected from a group consisting of cars, trucks, planes boats and robots.

8.(Previously Presented) A method of moving a plurality of model vehicles in formation, comprising the steps of:

providing motors and a control system in a first model vehicle, wherein said first model vehicle travels in along a first pathway;

providing at least one linkage element that extends from said first model vehicle at a predetermined angle, wherein said predetermined angle can be selectively adjusted by remote control by one of said motors;

physically coupling a remainder of said plurality of model vehicles to said at least one linkage, wherein said remainder of said plurality of model vehicles are moved in a formation by said first model vehicle along at least one pathway that differs from to said first pathway of said first model vehicle.

9.(Previously Presented) The method according to Claim 8, further including the step of selectively adjusting said formation as said remainder of said plurality of model vehicle are moved by said first model vehicle, by selectively adjusting said predetermined angle.

10.(Cancelled)

11.(Cancelled)

12.(Previously Presented) An assembly, comprising:

at least one linkage element;

a remotely controlled vehicle that moves along a first pathway as directed by remote control signals, wherein said at least one linkage element extends from said remotely controlled vehicle at a predetermined angle, and wherein said remotely controlled vehicle contains a motor that can selectively alter said predetermined angle ; and

at least one secondary vehicle physically connected to said at least one linkage element, wherein said at least one secondary vehicle is moved in formation by said remotely controlled vehicle along at least one secondary pathway that differs from said first pathway said remotely

controlled vehicle.

13. (Cancelled)

14. (Cancelled)

15. (Previously Presented) The assembly according to Claim 12, wherein said remotely controlled vehicle is a car and said at least one secondary vehicle is a car having generally the same shape and appearance.

16. (Currently Amended) A remotely controlled vehicle system, comprising:
a remote control signal transmitter for transmitting control signals;
a master model vehicle containing a remote control signal receiver, wherein said master model vehicle is controlled by said control signals as it travels along a first pathway;
a linkage element having a first end and an opposite second end, wherein said linkage element is pivotably connected to said master model vehicle at a middle point between said first end and said second end; and
plurality of slave model vehicles that are coupled to said master model vehicle and to each other by ~~at least one~~ said linkage element, wherein at least one of said plurality of slave ~~models~~ model vehicles is connected to said first end of said linkage element and at least one of said plurality of slave model vehicles is connected to said second end of said linkage element, wherein all of said plurality of slave model vehicles are propelled by said master model vehicle in a pathway ~~pathways~~ outside of said first pathway.

17. (Currently Amended) The system according to Claim 16, wherein said ~~at least one~~ linkage element causes all of said slave model vehicles to change position relative said master model vehicle when one of said slave model vehicle changes position relative said master vehicle.

18. (Cancelled)

19. (Currently Amended) The system according to Claim 16, wherein said master model vehicle contains a servo motor that is controlled by said remote control transmitter that selectively moves said ~~at least one~~ linkage element.